

## Jeti as primary back-channel

### Non compensated vario

Recommended as **starting** set for GPS Light class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **non-compensated**: On Jeti transmitter as Ex sensor value

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

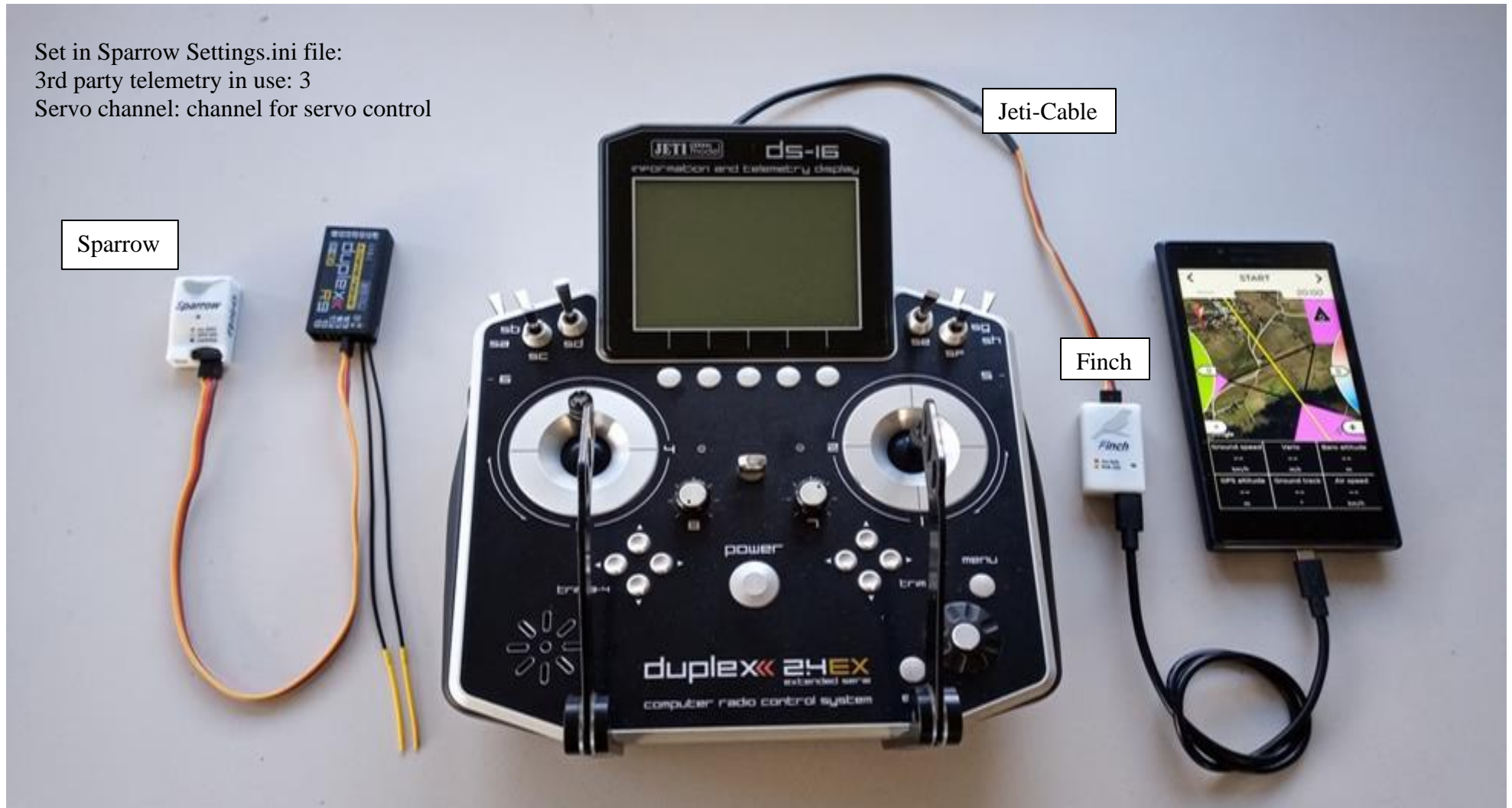
Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



## Jeti as primary back-channel

### Non compensated vario

Recommended as **advance** set for GPS Light class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **non-compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

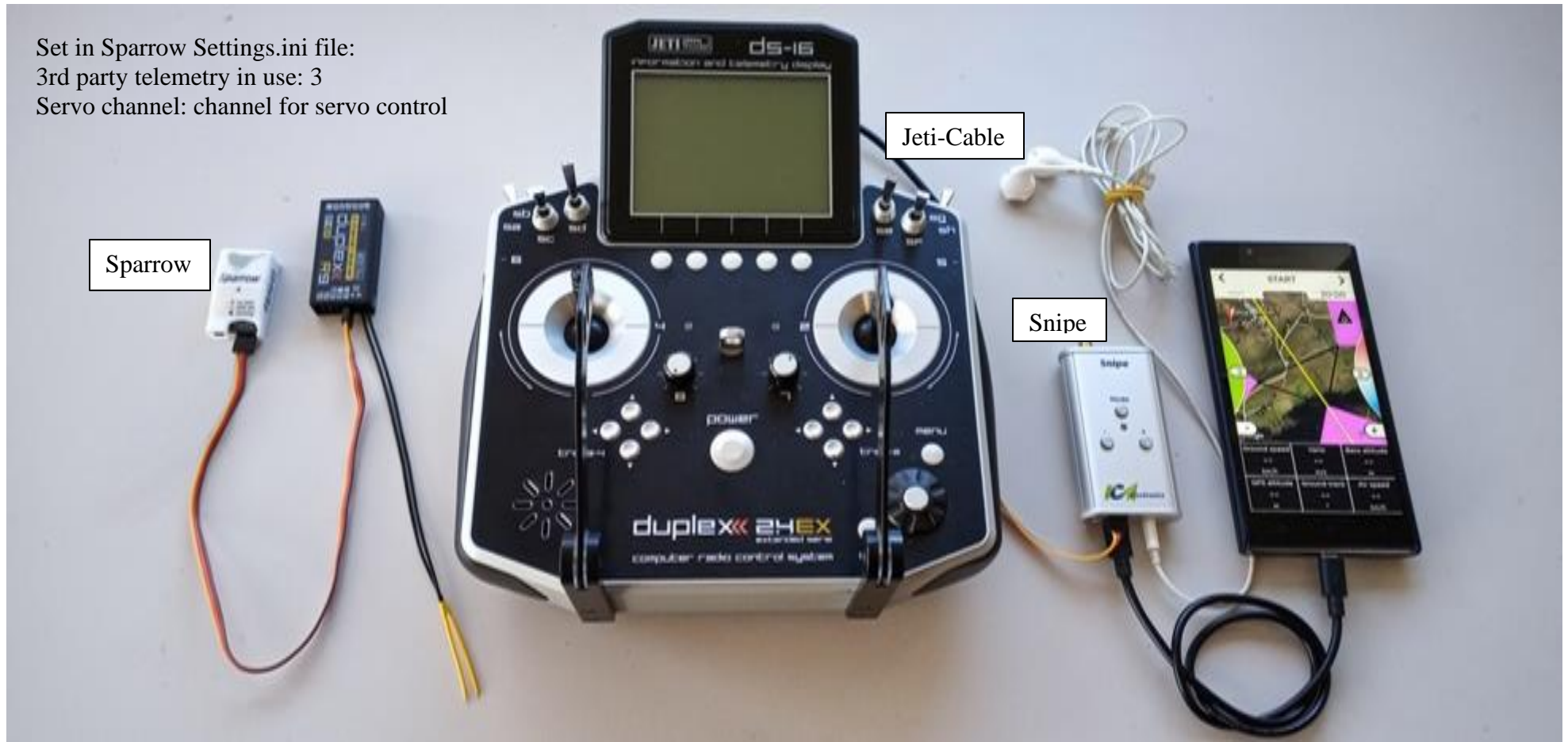
Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



## Jeti as primary back-channel Compensated vario

Recommended as **basic** set for GPS Sport class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **compensated**: On Jeti transmitter as Ex sensor value

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

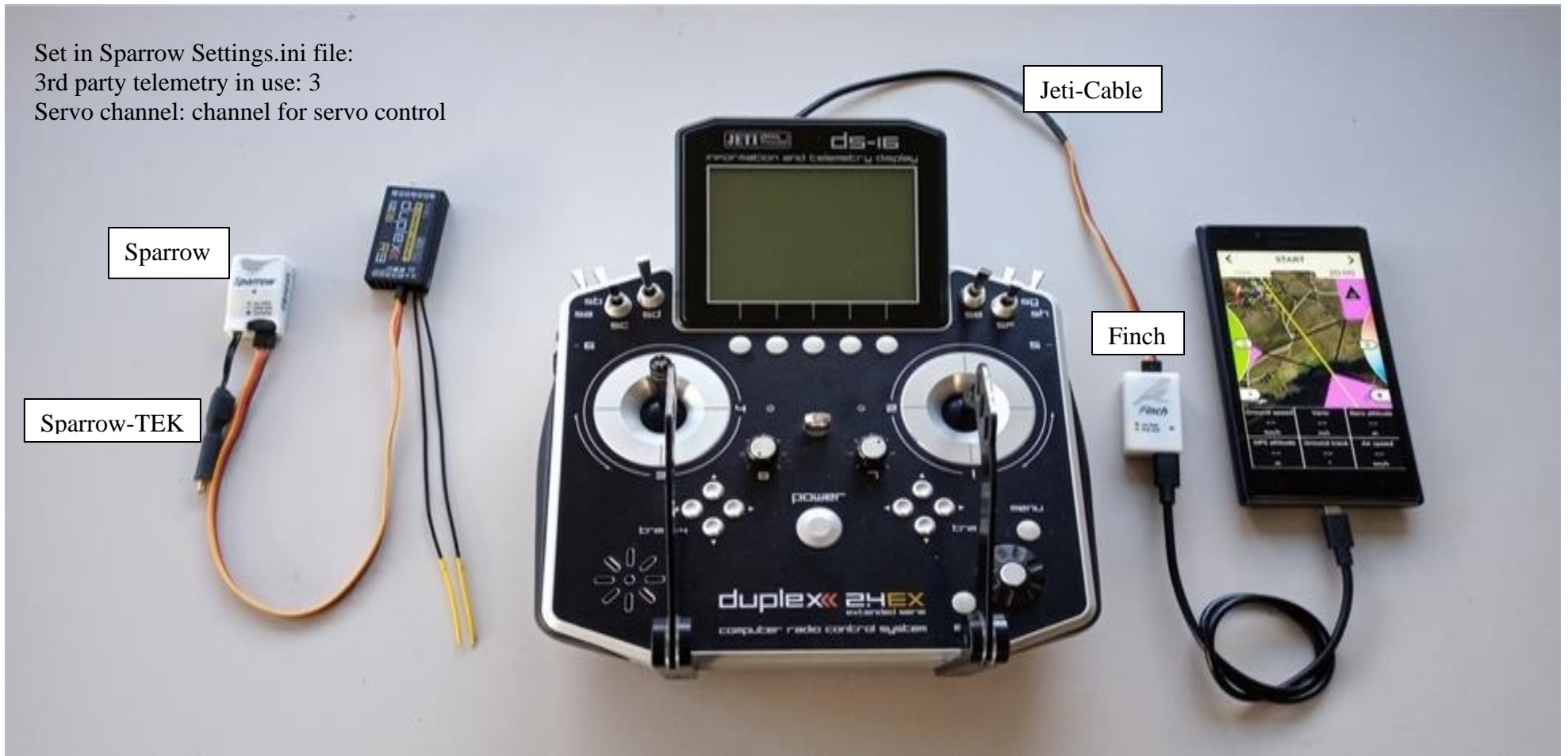
Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control





## Jeti as primary back-channel Compensated vario

Recommended as **advance** set for GPS Sport class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control



## Jeti as secondary back-channel Compensated vario RF module for primary RF link

Recommended as **pro** set for GPS Sport class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

**2<sup>nd</sup> RF link: yes, faster refresh rate and more stable link**

Set on Jeti PPM output connector: EX Data Stream  
On receiver EXT port must be set to EX Bus

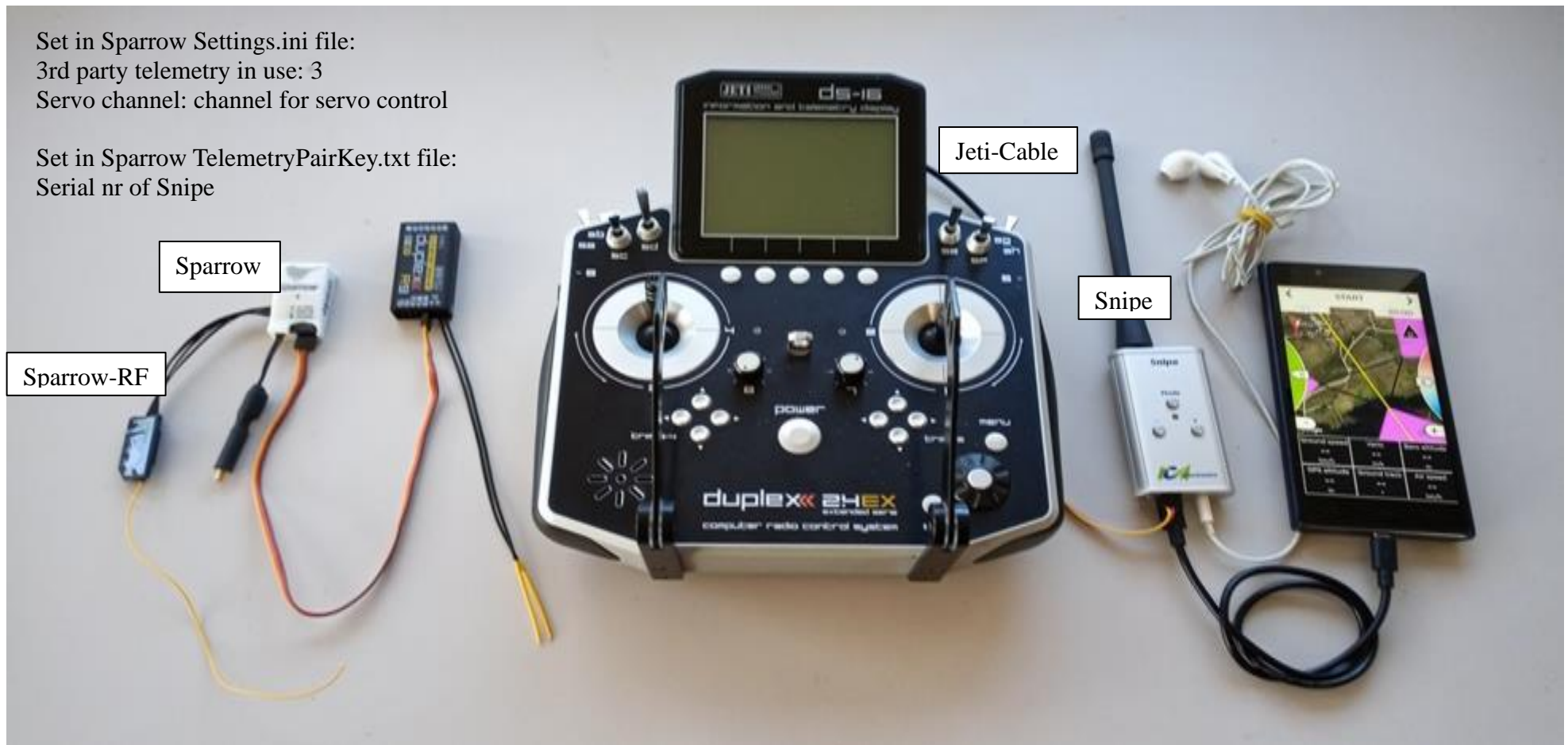
Set in Sparrow Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe



## Jeti as secondary back-channel

### Compensated vario

### RF module for primary RF link

Recommended as **pro** set for GPS scale and SLS class

**Jeti Cable is required and is installed inside Jeti transmitter!**

Vario **compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning, **stall**, **speed**

Beeps: yes

MacCready flying: **yes**

Servo control in Albatross: yes

**2<sup>nd</sup> RF link: yes, faster refresh rate and more stable link**

**Polar measurement: yes**

Set on Jeti PPM output connector: EX Data Stream

On receiver EXT port must be set to EX Bus

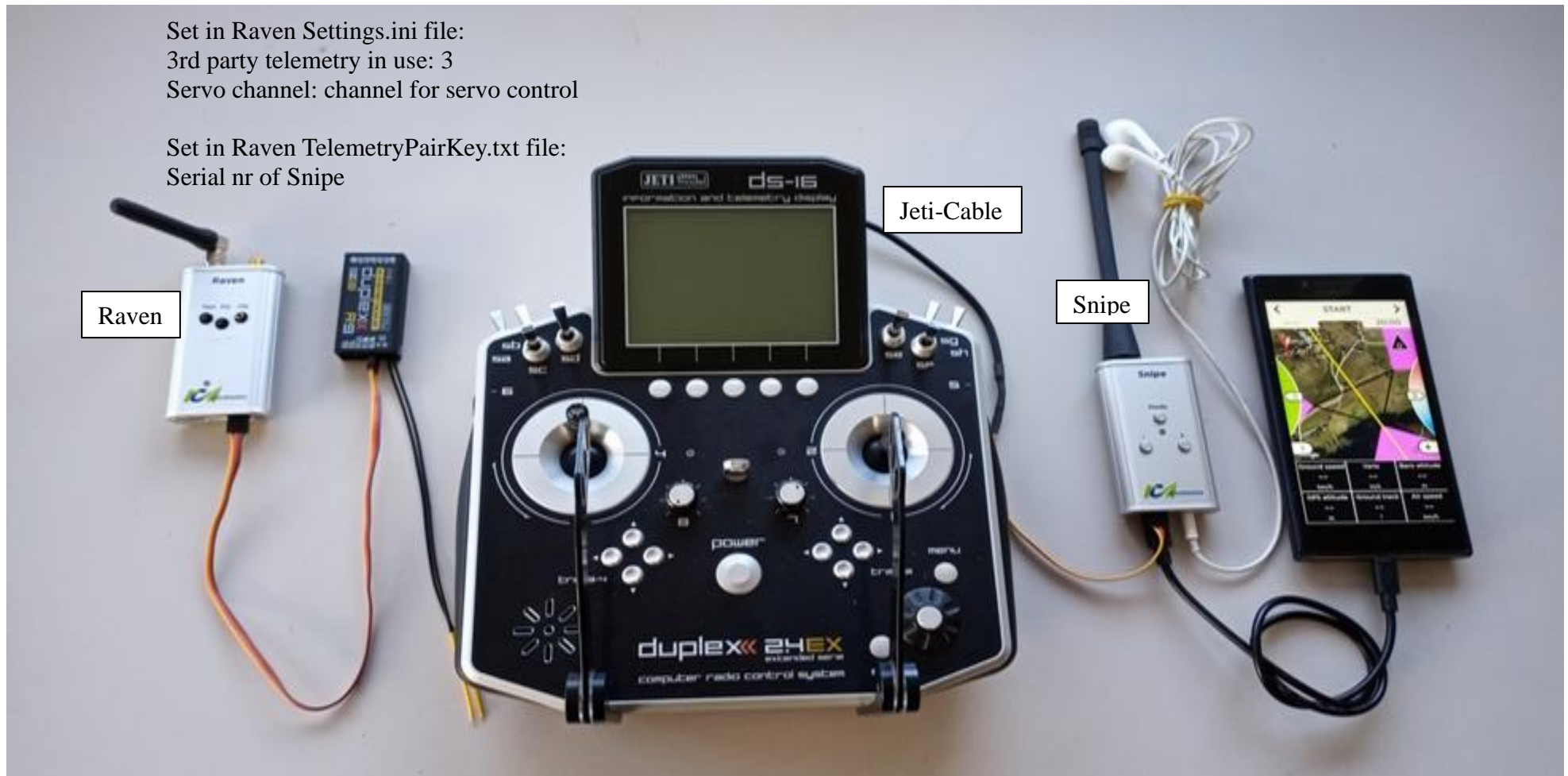
Set in Raven Settings.ini file:

3rd party telemetry in use: 3

Servo channel: channel for servo control

Set in Raven TelemetryPairKey.txt file:

Serial nr of Snipe





## System independent configuration

### Non compensated vario

Recommended as **starting** set for GPS Light class

Vario **non-compensated**: Coming soon: vario beep in Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Finch



## System independent configuration

### Non compensated vario

Recommended as **advance** set for GPS Light class

Vario **non-compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe





## System independent configuration Compensated vario

Recommended as **basic** set for GPS Sport class

Vario **compensated**: Coming soon: vario beep in Albatross

Stereo navigation: no

Voices in Albatross: Time remaining, lap count, start/restart, penalty points, inside

Beeps: no

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

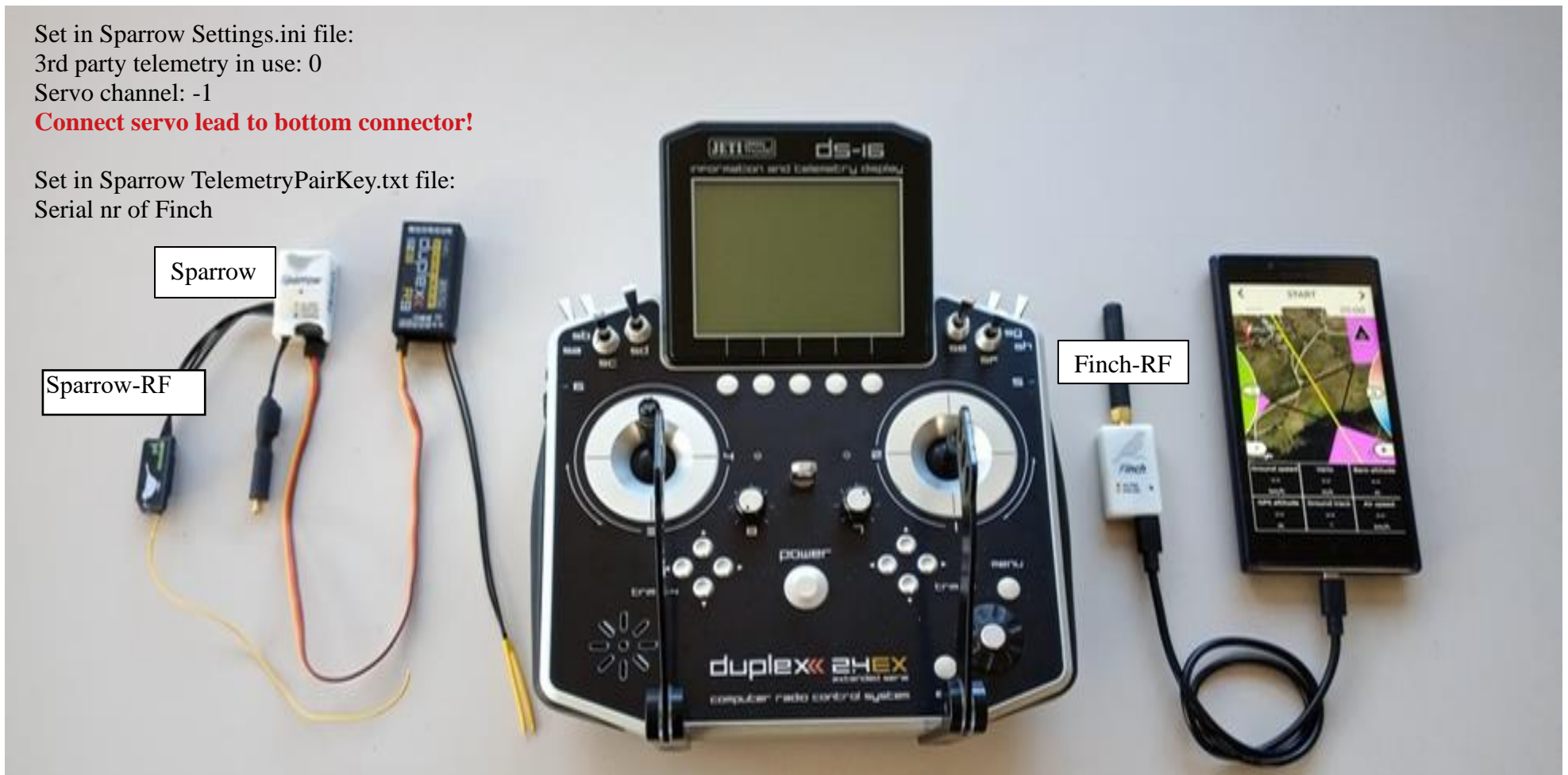
3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Finch



## System independent configuration

### Compensated vario

Recommended as **advance** set for GPS Sport class

Recommended as **basic** set for GPS Scale and SLS class

Vario **compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: no

Servo control in Albatross: yes

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of Snipe

Sparrow

Sparrow-RF

Snipe



## System independent configuration

### Compensated vario

Recommended as **pro** set for GPS Scale and SLS class

Vario **compensated**: On Snipe audio output

Stereo navigation: yes

Voices in Snipe: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning, **stall**, **speed**

Beeps: yes

MacCready flying: **yes**

Servo control in Albatross: yes

**Polar measurement**: yes

Set in Raven Settings.ini file:

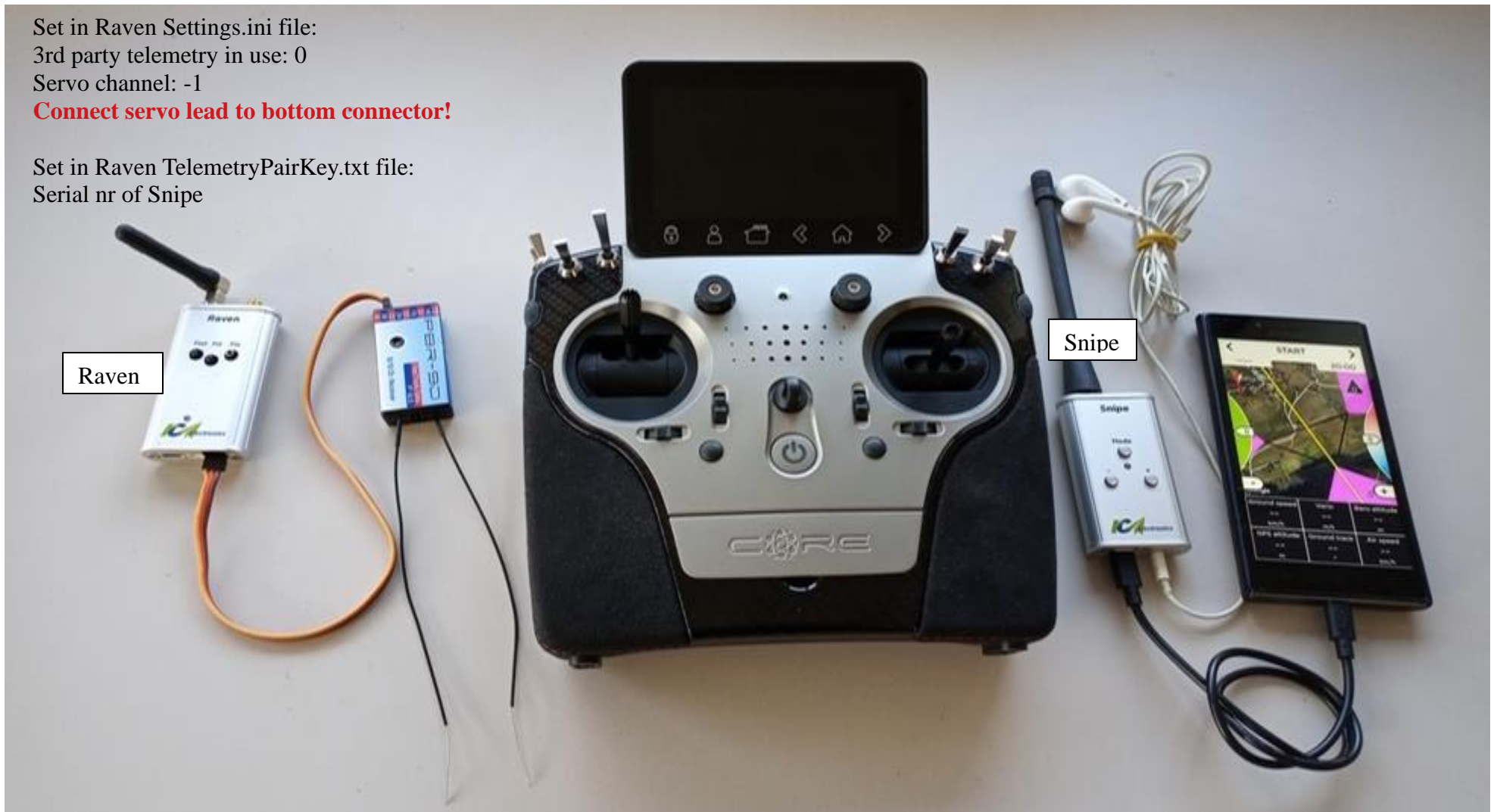
3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Raven TelemetryPairKey.txt file:

Serial nr of Snipe





## System independent T3000 configuration Compensated vario

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control for Start/restart: yes

**Polar measurement: no**

**Older system which is not available anymore. Due to GPS rules it is allowed only in scale class with no motor as Multi 2 system cannot detect motor.**



## System independent T3000 configuration Compensated vario + Albatross

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in Albatross: yes

**Polar measurement: no**

**Older system which is not available anymore. Due to GPS rules it is allowed only in scale class with no motor as Multi 2 system cannot detect motor.**

**T3000 cable is used for connection to Albatross**



## System independent T3000 configuration

### Compensated vario

Recommended for all: Light, Scale and SLS class

**T3000 requires v 3.x to work with Sparrow!**

Vario **compensated**: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in for Start/restart: yes

**Polar measurement: no**

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of T3000





## System independent T3000 configuration Compensated vario + Albatross

Recommended for all: Light, Scale and SLS class

**T3000 requires v 3.x to work with Sparrow!**

**T3000 cable is used for connection to Albatross**

Vario compensated: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in for Start/restart: yes

**Polar measurement: no**

Set in Sparrow Settings.ini file:

3rd party telemetry in use: 0

Servo channel: -1

**Connect servo lead to bottom connector!**

Set in Sparrow TelemetryPairKey.txt file:

Serial nr of T3000



## System independent T3000 configuration

### Compensated vario

Recommended for all: Scale and SLS class

**T3000 requires v 3.x to work with Raven!**

Vario compensated: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control for Start/restart: yes

**Polar measurement: yes**



## System independent T3000 configuration Compensated vario + Albatross

Recommended for all: Scale and SLS class

**T3000 requires v 3.x to work with Raven!**

**T3000 cable is used for connection to Albatross**

Vario compensated: On T3000 audio output

Stereo navigation: no

Voices in T3000: Time remaining, lap count, start/restart, penalty points, inside, off-course distance (in/out), altitude, altitude gain in thermal, average thermal, altitude warning, battery warning,

Beeps: yes

MacCready flying: **no**

Servo control in Albatross: yes

**Polar measurement: yes**

**Airspeed indicator in Albatross: yes**

